HD14076B

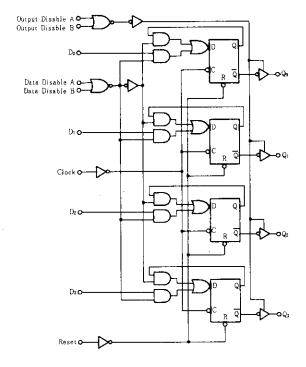
4-bit D-type Register

The HD14076B 4-bit Register consists of four D-type flip-flops operating synchronously from a common clock. OR gated output-disable inputs force the outputs into a high-impedance state for use in bus organized systems. OR gated data-disable inputs cause the Q outputs to be fed back to the D inputs of the flip-flops. Thus they are inhibited from changing state while the clocking process remains undisturbed. An asynchronous master reset is provided to clear all four flip-flops simultaneously independent of the clock or disable inputs.

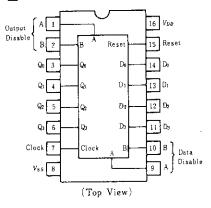
■ FEATURES

- Three-State Outputs with Gated Control Lines
- Fully Independent Clock Allows Unrestricted Operation for the Two Modes: Parallel Load and Do Nothing
- Asynchronous Master Reset
- For Bus Buffer Registers
- Quiescent Current = 5nA/pkg typ. @5V
- Supply Voltage Range = 3 to 18V
- Capable of Driving One Low-power Schottky TTL Load Over the Rated Temperature Range

■LOGIC DIAGRAM



■ PIN ARRANGEMENT



TRUTH TABLE

| | Output | | | | |
|-------|--------|--------|---------|------|----------------|
| D | CL 1 | Data I |)isable | Data |) |
| Reset | Clock | A | В | D | Q |
| 1 | × | × | × | × | 0 |
| 0 | 0 | × | × | . × | Q _n |
| 0 | 5 | 1 | × | × | Q, |
| 0 | | × | 1 | × | Q, |
| 0 | | 0 | 0 | 0 | 0 |
| 0 | | 0 | 0 | 1 | 1 |

Note) ×=Don't Care

When either output disable A or B (or both) is (are) high the output is disabled to the high-impedance state; however sequential operation of the flip-flops is not affected.

■ ELECTRICAL CHARACTERISTICS

| Characteristic | Symbo | $V_{bb}(V)$ Test Conditions | -4 | −40° C | | 25℃ | | | 85 ℃ | | |
|--|-----------------|-----------------------------|--|---------------|-------|-------|----------|------|-------------|------|----|
| Sharacto istic | S, mbol | | min | max | min | typ | max | min | max | Unit | |
| | | 5.0 | $V_{in} = V_{DD}$ or 0 | | 0.05 | | 0 | 0.05 | _ | 0.05 | v |
| Characteristic Output Voltage Input Voltage Output Drive Current Input Current Input Capacitance Quiescent Current Total Supply Current* | Voi | 10 | | | 0.05 | _ | 0 | 0.05 | _ | 0.05 | |
| | | 15 | | | 0.05 | _ | 0 | 0.05 | _ | 0.05 | |
| | | 5.0 | $V_{in}=0$ or V_{DD} | 4.95 | | 4.95 | 5.0 | | 4.95 | _ | v |
| | V _{OH} | 10 | | 9.95 | _ | 9.95 | 10 | _ | 9.95 | _ | |
| | | 15 | | 14.95 | | 14.95 | 15 | | 14.95 | | |
| ٠, | | 5.0 | $V_{\rm swf} = 4.5 \text{ or } 0.5 \text{ V}$ | _ | 1.5 | _ | 2.25 | 1.5 | _ | 1.5 | v |
| Input Voltage | V_{IL} | 10 | $V_{\rm ext} = 9.0$ or $1.0 m V$ | _ | 3.0 | _ | 4.50 | 3.0 | _ | 3.0 | |
| | | 15 | $V_{\rm ext} = 13.5 \text{ or } 1.5 \text{ V}$ | _ | 4.0 | | 6.75 | 4.0 | | 4.0 | |
| Input voltage | | 5.0 | $V_{\text{out}} = 0.5 \text{ or } 4.5 \text{ V}$ | 3.5 | | 3.5 | 2.75 | _ | 3.5 | | v |
| Input Voltage | V _{tH} | 10 | $V_{out} = 1.0 \text{ or } 9.0 \text{ V}$ | 7.0 | - | 7.0 | 5.50 | _ | 7.0 | | |
| | | 15 | $V_{out} = 1.5 \text{ or } 13.5 \text{ V}$ | 11.0 | _ | 11.0 | 8.25 | | 11.0 | _ | |
| | | 5.0 | $V_{OH}=2.5\mathrm{V}$ | -1.0 | _ | -0.8 | -1.7 | _ | -0.6 | _ | - |
| | Іон | 5.0 | $V_{OH}=4.6\mathrm{V}$ | -0.2 | _ | -0.16 | -0.36 | _ | -0.12 | _ | mA |
| | | 10 | $V_{OH} = 9.5 \mathrm{V}$ | -0.5 | _ | -0.4 | -0.9 | _ | -0.3 | _ | |
| Output Drive Current | | 15 | $V_{OH} = 13.5 \mathrm{V}$ | -1.4 | | -1.2 | -3.5 | | -1.0 | _ | |
| | | 5.0 | $V_{OL} = 0.4 \mathrm{V}$ | 0.52 | _ | 0.44 | 0.88 | | 0.36 | _ | mА |
| | IoL | 10 | $V_{oL} = 0.5 \mathrm{V}$ | 1.3 | _ | 1.1 | 2.25 | _ | 0.9 | | |
| | | 15 | $V_{0L} = 1.5 \mathrm{V}$ | 3.6 | _ | 3.0 | 8.8 | _ | 2.4 | | |
| Input Current | I.a | 15 | | _ | ±0.3 | | ±0.00001 | ±0.3 | | ±0.0 | μA |
| Input Capacitance | Cin. | | $V_{i*}=0$ | _ | | _ | 5.0 | 7.5 | | _ | pF |
| | | 5.0 | 7 0: 1 | | 20 | _ | 0.005 | 20 | _ | 150 | μA |
| Input Capacitance C_{is} $V_{is} = 0$ Quiescent Current I_{RR} 10 Zero S | Zero Signal, | _ | 40 | | 0.010 | 40 | | 300 | μA | | |
| | | 15 | per Package | _ | 80 | | 0.015 | 80 | -1 | 600 | |
| | I_{τ} | 5.0 | Dynamic $+I_{DD}$, | | _ | | 0.75 | _ | _ | _ | μA |
| Total Supply Current* | | 10 | per Gate, C _L =50pF | _ | | _ | 1.50 | _ | _ | | |
| | | 15 | $f=1\mathrm{kHz}$ | - | | _ | 2.25 | | • | | |

^{*} To calculate total supply current at frequency other than 1kHz.

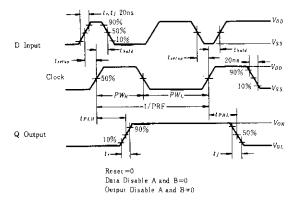
 $[@]V_{DD} = 5.0 \text{ V } I_T = (0.75 \, \mu\text{A/kHz}) f + I_{DD}, \ @V_{DD} = 10 \text{ V } I_T = (1.50 \, \mu\text{A/kHz}) f + I_{DD}, \ @V_{DD} = 15 \text{ V } I_T = (2.25 \, \mu\text{A/kHz}) f + I_{DD} = 10 \text{ V } I_T = (2.25 \, \mu\text{A/kHz}) f + I_{D$

SWITCHING CHARACTERISTICS ($C_L = 50 \,\mathrm{pF}$, $Ta = 25 \,^{\circ}\mathrm{C}$)

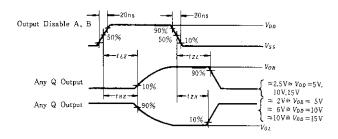
| Characteristic | | Symbol | $V_{DD}(\mathbf{V})$ | min | typ | max | Unit |
|--------------------------------|-------|----------------------|----------------------|--------------|-----|-----|--------------|
| | | | 5.0 | | 180 | 360 | |
| Output Rise Time | t, | 10 | _ | 90 | 180 | ns | |
| | | 15 | | 65 | 130 | | |
| Output Fall Time | | ŧ, | 5.0 | _ | 100 | 200 | ns |
| | | | 10 | - | 50 | 100 | |
| | | | 15 | | 40 | 80 | |
| | | | 5.0 | _ | 300 | 600 | ns |
| 154 | Clock | | 10 | | 125 | 250 | |
| | | t _{PLH} , | 15 | | 90 | 180 | |
| Propagation Delay Time | | t _{PHL} | 5.0 | | 300 | 600 | |
| | Reset | 1772 | 10 | _ | 125 | 250 | |
| | | | 15 | _ | 90 | 180 | |
| | | | 5.0 | _ | 150 | 300 | |
| Output Disable Time | | t _{HZ} , | 10 | | 60 | 120 | ns |
| | | . t _{LZ} | 15 | _ | 45 | 90 | |
| Output Enable Time | | | 5.0 | _ | 200 | 400 | ns |
| | | tzH, | 10 | _ | 80 | 160 | |
| | | t_{ZL} | 15 | _ | 60 | 120 | |
| Clock Pulse Width | | ₽Wc | 5.0 | 260 | 130 | | ns |
| | | | 10 | 110 | 55 | | |
| | | | 15 | 80 | 40 | | |
| | | PW _R | 5.0 | 370 | 185 | | ns |
| Reset Pulse Width | | | 10 | 150 | 75 | | |
| Reset Fulse Wigth | | | 15 | 110 | 55 | | - "" |
| | | | 5.0 | 30 | 15 | | + |
| Setup Time | | | 10 | 10 | 5 | | |
| Setup Time | | t _{attup} · | 15 | 4 | 2 | | ns |
| | | | + | | | | ļ |
| Hold Time | | | 5.0 | 130 | 65 | | ns |
| 110.4 I IIIIC | | Lauid | 10 | 60 | 30 | | |
| | | | | 50 | 25 | | |
| Data Disable Satur Tima | | | 5.0 | 220 | 110 | | - |
| Data Disable Setup Time | | ‡ setup | 10 | 80 | 40 | | ns |
| Clock Pulse Rise and Fall Time | | | 15 | 50 | 25 | | μs |
| | | tr, | 5.0 | - | _ | 15 | |
| | | t _f | 10 | _ | | 15 | |
| | | | 15 | | | 15 | |
| Clock Frequency | | PRF | 5.0 | | 3.6 | 1.8 | MHz |
| | | | 10 | <u> </u> | 9.0 | 4.5 | |
| | 1 | 15 | _ | 12 | 6.0 | | |

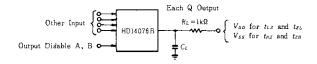
■ DYNAMIC SIGNAL WAVEFORMS

TIMING DIAGRAM



● Three-state Enable/Disable Delay





Unit: mm 19.20 20.00 Max 16 7.40 Max 6.30 1.3 1.11 Max 7.62 5.06 Max 2.54 Min 0.51 Min $0.25^{+0.13}_{-0.05}$ 0.48 ± 0.10 2.54 ± 0.25 $0^{\circ} - 15^{\circ}$ Hitachi Code DP-16 **JEDEC** Conforms EIAJ Conforms Weight (reference value) 1.07 g

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