specifications for micro dot printer Model-150II

October II, 1984

Rev. 2



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Summary

Model-150II is the mechanical dot printer, whose Print Head consists of 4 Print Solenoids laying horizontally and moves for 24 dots horizontally. Print Head which moves horizontally prints unidirectionally as each Print Solenoid of it is energized in order. When Print Head return, paper is fed for 1 pitch automatically. By repetition of this dot line printing and paper feed desired Print Format can be obtained.

It is characterized by the following features:

- 1. Clear dot printing
- 2. Small-size, Light weight (60g) and Super thin thickness (12.8mm)
- 3. 44,5mm width normal paper
- 4. Ni-Cd Battery Drive
- 5. Low price



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1. General Specifications

1.1 Printing Method:

1.2 Print Format

1) Number of Total Dot:

. 2) Number of Column:

1. 3 Print Speed

1) 1 Dot Line:

2) 5x 7 dot Matrix:
 (3 dots line space)

1. 4 Character Size

1) Dot Space:

2) 5x7 Dot Matrix:

1. 5 Paper:

1. 6 Paper Feed:

1.7 Inking:

. 1.8 Motor

1) Terminal Voltage:

2) Mean Current:

1. 9 Timing Detector:

1. 10 Reset Detector:

1. 11 Print Solencid

1) Terminal Voltage:

Impact Dot Matrix Printer

Max. 96 dots/1 dot line

Max. 16 Columns (In case of 5x7 dot matrix and 1 dot column space)

Approx. 100 ms (continous printing, . 4.5VDC, 25°C)
Approx. 1 l/s (continuous printing, 4.5VDC, 25°C)

Horizontal 0.35 mm Vertical 0.35 mm

 $1.8 \text{ (W)} \times 2.5 \text{ (H)mm}$

44.5 mm width woodfree paper

Paper is fed automatically per dot line. With paper free mechanism

Ribbon Cassette Ribbon is fed automatically during Motor revolution.

4. 5+45VDC

Approx.0.17 A (4.5VDC, 25°C)

Tachometer-Generator (directly connected with motor)

Reed-Switch

4 columns/sol. x 4 pcs of Solenoids

4, $5 \pm \frac{0.5}{1.2}$ VDC

Note: Print Solenoid terminal voltage and Motor terminal voltage should satisfy the voltage relationship which is shown in item 2.8.1).

1. $5\Omega \pm 0.15 \Omega$ (at 25°C)

2) Ohmic Resistance:

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1.12 Connection

1) Printer side:

P. C. Board with 2.54mm pitch

cupper leaf patern that is fixed on

printer frame.

Cable wires or Lead wires

2) Circuit side :

1.13 Ambient Temperature Operating: 0°C to 50°C

L 14 Reliability:

MCBF 5x10 5 lines

1.15 Dimensions:

73.2 (W) x 42.6 (D) x 12.8 (H)mm

L. 16 Weight:

Approx. 60.g

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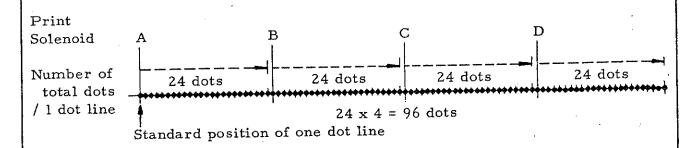
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2. Detail Specifications

2.1 Print Format

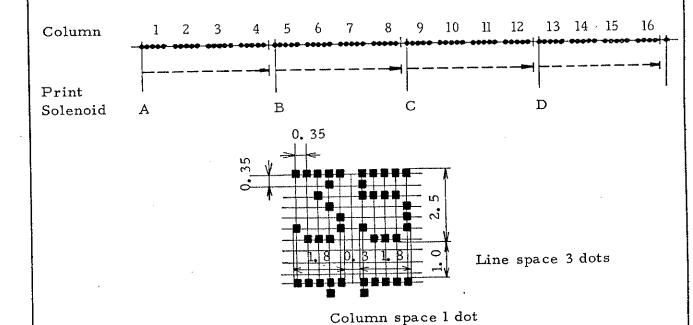
Print Head consists of 4 Print Solenoids (A. B. C. D) which are laid horizontally. Print Head moves to right direction from left side on stand-by condition. Moving amount of Print Head is 24 dots per Print Solenoid. One dot line is formed by energizing Print Solenoid one by one as Print Head is moving. Number of total dots per dot line is 96 dots (24 dots × 4 Print Solenoids)



1) 5x7 Dot Matrix

Divide 24 dots which one Print Solenoid is printable into four equal parts. And 6 dots in one part are used as one column; That is 5 dots for printing and one dot for column space. Accordingly one dot line is formed of 96 dots which are divided into 16 parts and 5x7 dot matrix character can be got by repeating 7 times in the direction of paper feed. Number of columns is 16.

 $(5+1) \times 16 = 96 \text{ dots} / 1 \text{ dot line}$



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2.2 Paper Feed

1) One dot line Feed:

Paper is fed automatically for 0.35mm (one pitch) when Print Head is returned

to left from right side.

2) Space Feed:

Line space feed is done by feeding one

dot line continuously.

3) Paper Free Mechanism:

Paper can be pulled out forward when

the printer is in the halted state.

4) Manual Paper Feed Knob:

Option

2. 3 Ribbon Cassette

1) Color:

Purple or Black

2) Dimensions:

Approx. $74 \text{ mm}(W) \times 25 \text{mm}(D) \times 7 \text{mm}(H)$

3) Life:

Purple Approx. 1 x 10⁴ lines

(4.5VDC 25°C continuous printing)

Black Approx. 7×10^3 lines

(4.5VDC 25°C continuous printing)

(Life test is done with print mode in

Attached Table 1.)

4) Parts number:

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' 2.4 Paper

1) Kind:

2) Width:

Woodfree paper $44.5 \pm 0.5 \text{mm}$

3) Diameter:

Max. \$ 50mm

4) Thickness:

Approx. 0.07mm

5) Basis weight:

 $52.3g/m^2 (141b/500 \text{ sheet/}17^n \times 22^n)$

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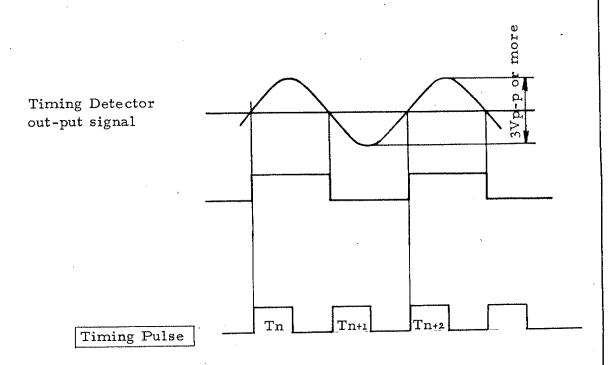
2.5 Timing Detector

Timing Detector is tachometer-generator that is directly connected with motor. Detector generates 168 out-put signals per dot line; 96 out-put signals correspond to dot position of Print Head and 72 out-put signals correspond to Print Head return. These out-put signals are arranged in a pulse wave form on the customer side, and are used as Timing Pulse.

1) Timing Pulse:

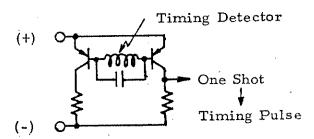
Timing Pulses should be obtained for threshold level to be 0 ± 1 V of Timing Detector out-put signal.

2) Out-put Wave Form



denotes the signal to be generated by the customer side.

⟨Wave shaping circuit⟩
(Reference)





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2.6 Reset Detector

Reset Detector has Lead-Switch that makes at each time of dot lines. Reset Detector out-put signal is used as Reset Signal which denotes standard position of dot position at each time of print cycles.

1) Rating:

Voltage

2.85VDC - 20VDC

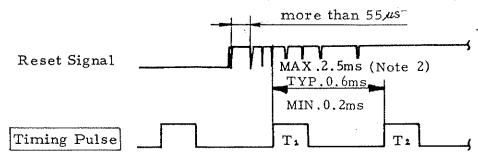
Current

20µA - 1mA

Instantaneous power 5mW or less

(Resistance load)

2) Pulse Wave Form, Phase

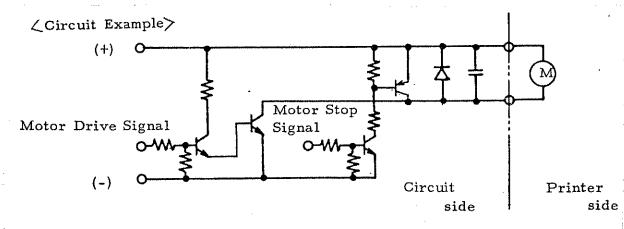


- Note 1. ____ denotes the signal to be generated by the customer side.
 - During motor steady driving (except for period from motor starting to generation of Reset signal R₁)

2.7 Motor

1) Driving and Stopping

The motor is in the halted state when the printer is in the stand-by state (i. e., non-printing condition). Application of electric brake to quikly stop the motor must be performed by interrupting Motor Drive Signal within 0.5ms after the leading edge of Reset Signal Rn (Rn is R₁₀ in case of 5x7 dot matrix and 3 dots line space.), and applying the Motor Stop Signal more than 100ms, and short-circuiting across the Motor terminals with a transistor.



2) Stopping at abnormality Motor driving signal is cut off before the interval of timing pulse $(Tn \sim Tn_{+1})$ is performed more than 1 second.



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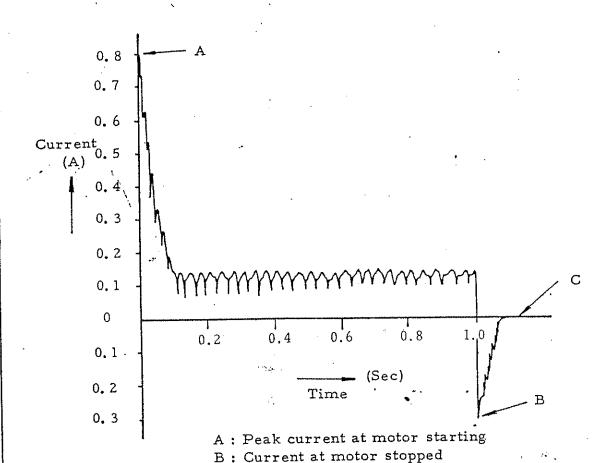
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3) Terminal Voltage:

4. 5 $\pm \frac{0.5}{0.7}$ VDC

- 4) Current
 - a) Peak Current:
 - b) Mean Current:
 - c) Current wave form

Approx. 0.8A (4.5VDC, 25°C) (Worst casel.2 A or less) Approx. 0.17 A (4.5VDC, 25°C)



C: Halted state

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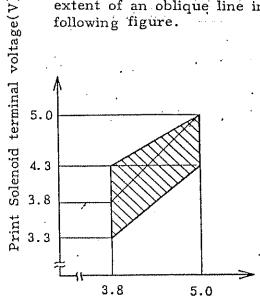
2.8 Print Solenoid

Dot Print is done by energizing Print Solenoid.

1) Terminal Voltage:

4. 5±1.2 VDC

Print Solenoid terminal voltage and Motor terminal voltage should satisfy the voltage relationship of the extent of an oblique line in the following figure.



Motor terminal voltage(V)

- 2) Ohrnic Resistance:
- 3) Current:
- 4) Pulse Width:
- 5.) Watt consumption:
- 6) Energizing Duty:
- 7) Continous Energizing:
- 8) Spark Killer:
- 9) Protection of solenoid at abnormality:

- 1. $5\Omega \pm 0.15\Omega$ (at 25°C)
 - 3 A/Print Solenoid (Peak current)

From the leading edge of Timing signal Tn to the leading edge of Timing signal Tn+1 (See following figure)

3mj/dot

1/4

One Print Solenoid can be energized continuously by 400 dot lines (24 x 400 = 9600 dots). But it is necessary to take non-printing time longer than continuous energizing time.

Prepared by the customer side refer the circuit and case design recommendations.

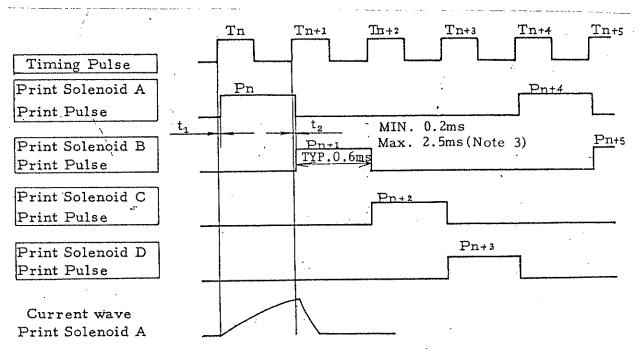
Energizing pulse to solenoid should be cut off less than 1 sec.

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denotes the signal to be generated by the customer side.

Note; 1. $t_1 = t_2 \le 50 \mu \text{ s}$

- 2. In case of printing 5x7 matrix character, Print Solenoid A is energized with Print Pulse Pn which has Pulse width of Timing signal Tn to Tn+1, and nest Print Solenoid B is energized with Print Pulse Pn+1 which has Pulse width of Timing signal Tn+1 to Tn+2. In the same way Print Solenoid C is energized with Print Pulse Pn+2, Print Solenoid D is energized with Print Pulse Pn+3, and the Print Solenoid A is energized with Print Pulse Pn+4 again. As upper mentioned four Print Solenoids should be energized according to the order of Print Solenoid A, B, C, D.
- 3. Max 2.5ms: During motor steady driving (except for period from motor starting to generation of Reset signal R_I)



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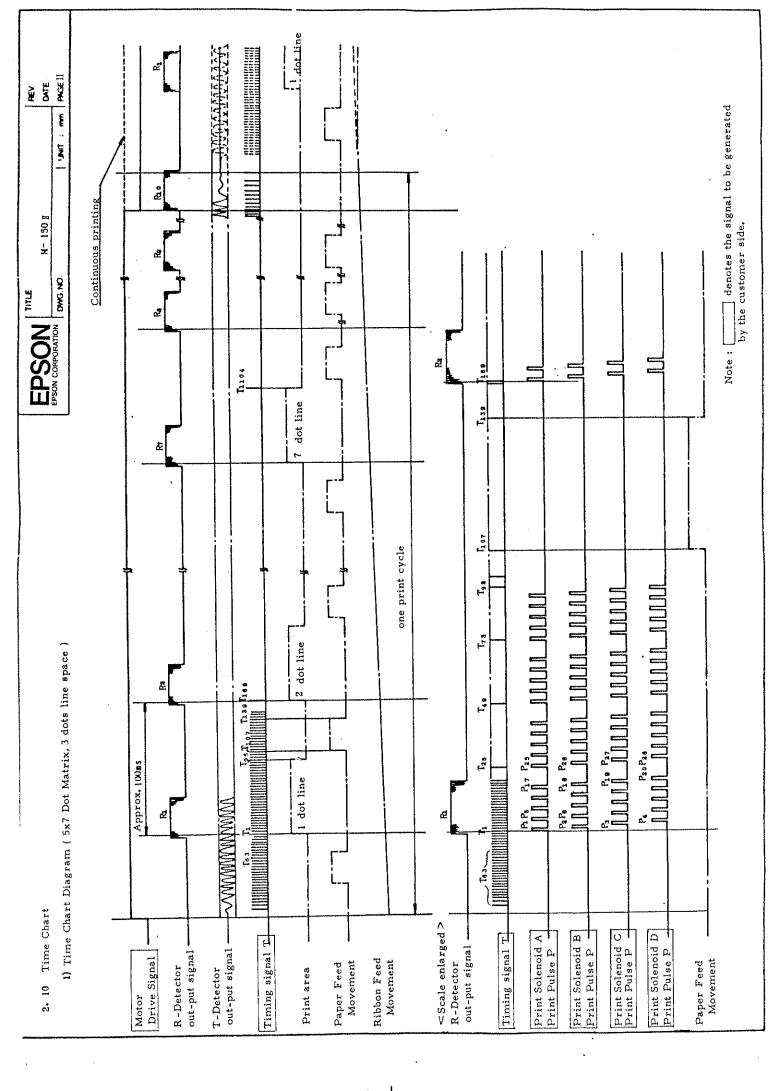
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2.9 Terminal Assignment

Connection	n.	Ter	minal No.	
Reset Detector		1	0	
"		2	0	
Motor (-)		3	0	M
/ (+)		4	0	
Print Solenoid	common	5	0	
Print Solenoid	(D)	6	0	***************************************
4	(C)	7		300000
	(B)	8	-	70000
. "	(A)	9	o——	•••••
Timing Detect	or	10	0	2000000
1		11	6	

Note; Terminal numbers are 1, 2, 11 from left side of cupper leaf patern on P. C. Board. (See 2.11 Overall Dimensions)



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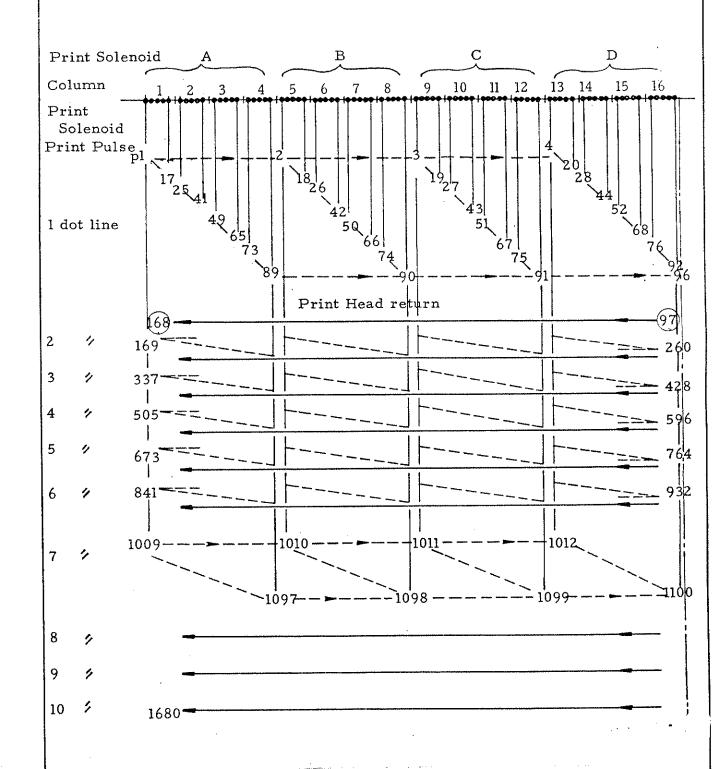
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2) Detail Timing Pulse distribution (5x7 Dot Matrix, 3 dots line space)

Pn= Tn ~Tn+1 (Pn; Print Pulse, Tn; Timing Pulse)





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Print Solenoid A is energized with Print Pulse P1 of Timing Pulse T1 to T2, and the left-upper-most dot of first column character is printed. Next Print Solenoid B is energized with Print Pulse P2 of Timing Pulse T2 to T3, and the left-upper-most dot line of 5th column characters is printed. Upper-mentioned control is done in order, and Print Solenoid D is energized with Print Pulse P92 of Timing Pulse T92 to T93, and the right-upper-most dot of 16th column characters is printed.

Column space of 4 th, 8th, 12th and 16th column are kept one dot, and Print Head is returned to home position between Timing signal T% and T168. And paper is fed automatically one dot. Upper-mentioned movement is done continuously through 7 dot lines, and Print Solenoid D is energized with Print Pulse P1000 of Timing Pulse T1100 to T1101, and the right-down-most dot of 16th column characters is printed. And printing of 5x7 dot matrix character has completed. Next, to keep 3 dots line space, paper is fed in 3 dots line; that is 8,9 and 10 dot line, and one print cycle has completed at Timing signal T1600.

3) Discrimination of R₁ and R signal

After the motor is started by applying Motor Drive Signal, Timing Signal should be counted. The Reset Signal after 63 times of Timing Signal counting should be set as R₁ signal. After R₁ signal is set, the Reset Signal from R₂ to Rn is set as same as R₁ signal is set. Initial Setting to confirm that Print Head is set at the stand-by state is completed by detecting R₁ signal. Timing signal T₁ that shows standard dot position of each one print cycle is determined by detecting R₁ signal.

4) Continuous printing or continuous Paper feed

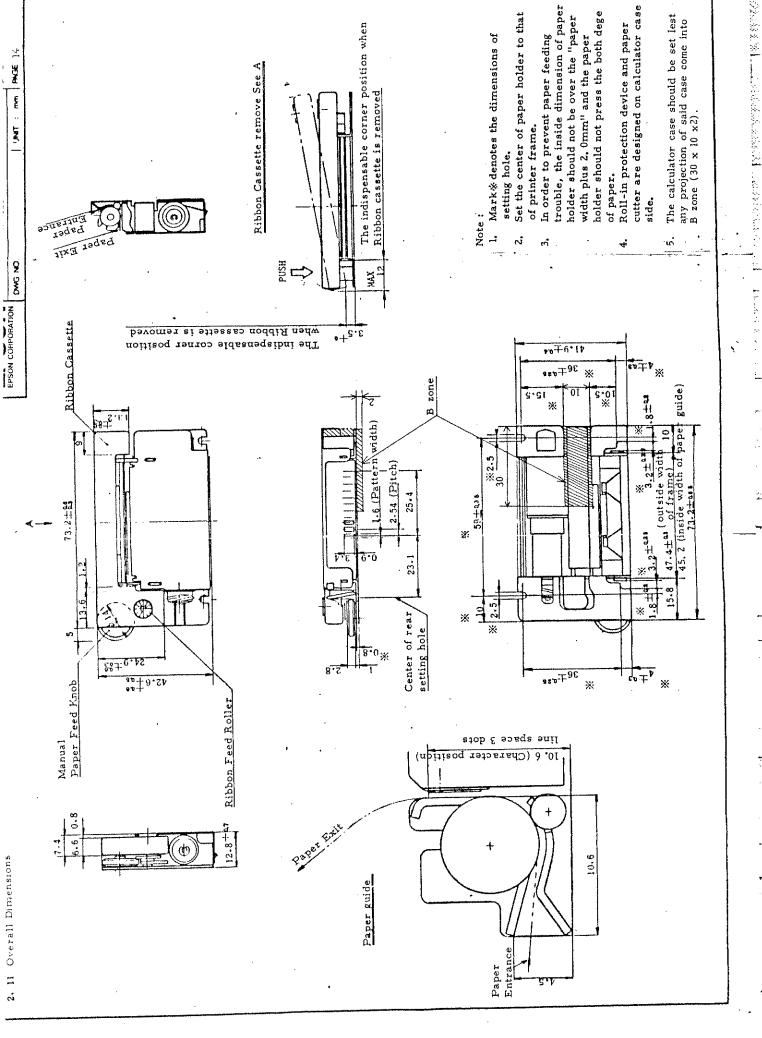
It is performed by applying Motor Drive Signal continuously without interrupting Motor Drive Signal.

5) Reset Signal

Reset Signal does not sometimes make at stand-by state.

Note;

- 1. More than 63 Timing Pulses are generated between Motor starting and generation of R1 signal.
- 2. Term of energizing Print Solenoid prohibitted
 - 1) From Motor starting to the leading edge of R₁ signal (from Motor starting to regular revolution)
 - 2) From Timing Signal T97+168n to T168+168n (Term of Print Head Return; n is from 0 to 10)
 - 3) Print Solenoid Print Pulse should not be energized and interrupted with electric noise.
 - 4) After the Reset Signal R1 is confirmed per each one print cycle, count of Timing Signal should be cleared per each one print cycle.





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Attached Table l Print Mode

0123456789:; <=>? 123456789:;<=>?@ 23456789:;<=>?@A 3456789:;<=>?@AB 456789:;<=>?@ABC 56789:;<=>?@ABCD 6789:;<=>?@ABCDE 789:;<=>?@ABCDEF 89:;<=>?@ABCDEFG 9:;<=>?@ABCDEFGH :;<=>?@ABCDEFGHI ;<=>?@ABCDEFGHIJ <=>?@ABCDEFGHIJK =>?@ABCDEFGHIJKL >?aascoeFGHIJKLM ?@ABCDEFGHIJKLMN **SABCDEFGHIJKLMNO ABCDEFGHIJKLMNÖP** BCDEFGHIJKLMNOPQ CDEFGHIJKLMHOPQR DEFGHIJKLMMOPQRS EFGHIJKLMNOPQRST FGHIJKLMNOPQRSTU



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****		M-150II SPEC, REVISION	
REV. NO.	PAGE	DESCRIPTION	DATE
1	1	1.3 Print Speed "Print condition" is added. 1.5 Paper Paper width is "44,5mm", was "45mm". 1.11 Print Solenoid "Terminal voltage" is changed.	September 10, 1983
	4	2.3 Ribbon cassette "Life" is added. "Print condition" is added.	
	6	2.6 2) Wave form, Phase "TYP.0.6ms" is added. "MIN.0.2ms" is added.	
	8	2.8 Print Solenoid "Terminal voltage " is changed. 3) Current "Current value" is "3A", was "2.5A".	
		8) Spark Killer "Prepared by the customer side refer the circuit and	
	9	case design recommendations! Note: Note 1 is " $t_1 = t_2 \le 50 \mu s$ ", was " $t_1 = t_2 \le 28 \mu s$ ".	
	3, 12,13	Column number is "l column, 2 column, 3 column from left side", was "l column, 2 column, from right side".	
	14	2.11 "Overall Dimensions" is changed.	
	15	"Attached Table 1" is added.	
2	6	2.6 2) Pulse Wave Form, Phase "MAX 2.5ms" is added. 2.7 2) "stopping at abnormality" is added.	October 11, 1984
	8	2.8 9) "protection of Solenoid at abnormality" is added.	
	9	Max 2.5ms is added.	
		;	