Technical introduction

1. General points

In order to provide optimum performance of semi-conducting devices it is essential not to exceed the maximum junction temperature indicated by the manufacturer.

Generally this maximum junction temperature can only be maintained without exceeding it by running the device concerned at lower power outputs.

At outputs approaching the maximum ratings semi-conductor devices have to be cooled by so called heatsinks, sometimes called dissipators.

The thermal performance of these heatsinks primarily depends on the thermal conductivity of the material from which they are made, size of surface area and mass.

In addition, surface colour, mounting position, temperature, ambient air velocity and mounting place all have varying influence on the final performance of the heatsink from one application to another..

However, a figure for thermal resistance can be experimentally determined in a reliable manner and used in the equations that follow in part 2.

There are no agreed international standard methods for testing electronic cooling systems or for the determination of the thermal resistance.

Therefore the diagrams and values given in our catalogue have been determined under practical operating conditions and therefore allow the most suitable heatsink from the range to be selected.

We expressly point out that all information and data is given to the best of our knowledge and belief. The user is solely responsible for the proper use of our products and he should check their suitability for the intended application.

Fischer Elektronik do not assume any warranty, whether expressed or implied, for the suitability, function or merchantibility of their products in specific or general applications, and they cannot be held liable for accidental or consequential damage due to non-observance of the above.

Furthermore Fischer Elektronik reserve the right to carry out technical modifications to their products at any time. All orders are subject to the General Sales Conditions of Fischer Elektronik.

2. The determination of thermal resistance

The thermal resistance is the parameter that is the most important in cooler selection, apart from mechanical considerations.

For determination of the thermal resistance the following equation applies:

Equation 1:
$$R_{thK} = \frac{\vartheta_i - \vartheta_0}{P} - (R_{thG} + R_{thM}) = \frac{\Delta \vartheta}{P} - R_{thGM}$$

In case of an application where the maximum junction temperature is not exceeded the temperature has to be verified. When the case temperature has been measured the use of the following equation will enable the maximum junction temperature to be calculated:

 $\vartheta_i = \vartheta G + P \times R_{th}G$ Equation 2:

The meaning of the determinants:

- = maximum junction temperature in °C of the device as indicated by manufacturer. θi As a »safety factor« this should be reduced by 20-30 °C.
- = ambient temperature in °C. ϑυ The rise in temperature caused by radiant heat of the heatsink should be increased by a margin of 10-30 °C.
- ∆ϑ = difference between maximum junction temperature and ambient temperature.
- ϑG = measured temperature of device case (equation 2).
- Ρ = maximum power rating of device in watts
- = thermal resistance in K/W R_{th}
- = internal thermal resistance of semiconductor device (as indicated by manufacturer) RthG

A 11 - 12 A 123 - 136 A 18 - 20

A 2

Figeher elektronik 23 Technical introduction

RthM = thermal resistance of mounting surface. For TO 3 cases the following approximate values apply:

1. dry, without insulatar	0.05 - 0.20 K/W
2. with thermal compound/without insulator	0.005 - 0.10 K/W
3. Aluminium oxide wafer with thermal compound	0.20 - 0.60 K/W
4. Mica wafer (0.05 mm thick) with thermal compound	0.40 - 0.90 K/W

RthK = thermal resistance of heatsink, which can be directly taken from the diagrams

 $R_{th}GM = sum of R_{th}G and R_{th}M$. For parallel connections of several transistors the value $R_{th}GM$ can be determined by the following

Equation:
Equation 3:
$$\frac{1}{R_{th}GM \text{ ges.}} = \frac{1}{R_{th}G1 + R_{th}M1} + \frac{1}{R_{th}G2 + R_{th}M2} + \dots + \frac{1}{R_{th}Gn + R_{th}Mn}$$

The result can be substituted into equation 1.

K = Kelvin, which is now the standard measure of temperature differences, measured in °C, therefore 1°C = 1 K.

K/W = Kelvin per watt, the unit of thermal resistance.

Calculation examples:

1.A TO 3 power transistor with 60 watt rating has a maximum junction temperature of 180 °C and an internal resistance of 0.6 K/W at an ambient of 40 °C with aluminium oxide wafers. What thermal resistance is required for the heatsink?

given: P = 60 W ϑ_i = 180 °C - 20 °C = 160 °C (for safety margin) ϑ_u = 40 °C RthG = 0,6 K/W RthM = 0.4 K/W (average value)

find:
$$R_{thK}$$
 using equation 1 $R_{thK} = \frac{\vartheta_i - \vartheta_u}{P} - (R_{thG} + R_{thM}) = \frac{160 \circ C - 40 \circ C}{60 W} - (R_{thG} + R_{thM}) = \frac{1.0 \text{ K/W}}{100 \text{ K}}$

2.Same conditions as above but for three devices with equally distributed power ratings.

solution use equation 1 and equation 3

$$\frac{1}{R_{thGM ges.}} = \frac{1}{0.6 + 0.4 \text{ K/W}} + \frac{1}{0.6 + 0.4 \text{ K/W}} + \frac{1}{0.6 + 0.4 \text{ K/W}} = \frac{3}{1} \text{ W/K}$$

$$R_{thGM ges} = \frac{1}{3} \text{ K/W} = \underline{0.33 \text{ K/W}}$$

substitute into Equation 1 gives:

$$R_{\text{thK}} = \frac{160 \text{ °C} - 40 \text{ °C}}{60 \text{ W}} - 0,33 \text{ K/W} = \frac{1,67 \text{ K/W}}{1,67 \text{ K/W}}$$

With these values determined, the tabulation on page A 13 - 17 can be used to give a choice of possible heatsink profiles. Then by examination of the drawings and curves the final choice can be made.

3.A transistor with power rating of 50 W and internal thermal resistance of 0.5 K/W has a case temperature of 40 °C. What is the actual value of junction temperature?

données:

P = 50 W $R_{thG} = 0.5 K/W$ $\vartheta_G = 40 ^{\circ}C$ find: ϑ_i using equ

d: ϑ_i using equation 2

$$\vartheta_i = \vartheta_G + (P \bullet RthG)$$

ϑ¡ = 40 °C + (50 W • 0,5 K/W) = 65 °C

A 3

Profilés aluminium standard
Dissipateurs extrudés→ A 133 - 134
→ A 22 - 83Dissipateurs à lamelles
Dissipateurs a liquide→ A 127 - 128
→ A 129 - 131

Matériel thermo-conducteur Perforations Perforations pour SSR Notes techniques $\overrightarrow{} E 2 - 22$ $\overrightarrow{} A 21$ $\overrightarrow{} A 12$ $\overrightarrow{} A 2 - 7$

Technical introduction

Thermal resistances of any profiles with forced convection

R _{thKf} R _{thKf} R _{thK} a	 a • RthK = thermal resistance with forced convection = thermal resistance with natural convection = factor of proportion
a	= factor of proportion



Remarks:

1. The values indicated in the diagrams apply only for heatsinks with black anodised surface, mounted vertically and natural convection.

Correction factors: natural surface: +10 to 15 % for horizontal mounting: + 15 to 20 %

2. Heatsink profiles are extruded to European standard DIN EN 12020 (former DIN 17615). For profiles exceeding a circumscribed circle of 300 mm, the tolerances to DIN EN 755 (former DIN 1748) apply.

Important note:

Manufacturers of certain electronic components, especially modules with a large surface area, IGBT etc., specify installation surfaces for heatsinks etc. with an flatness, which is beyond standard tolerances. Such perfect flatness can only be achieved by milling the installation surface. Furthermore, it should be noted that threaded wire inserts may be required in order to reach higher tightening torques in aluminium (e.g. Heli-Coil or similar.). Please observe the semiconductor manufacturers' information.

- 3. The mentioned heatsink profiles in our catalogue contain so called extrusion marks between the fins for a profile identification. To avoid misuse the operator has to check the size and position for the mechanical treatment or placement of the components.
- 4. Profile extruded threaded channels are no threads conforming to standards, as they have no thread pitch. The thread pitch is imitated by staggered webs (ribs). The customer is responsible for appropriate use.
- 5. Machining of our extruded and non extruded profiles conforms to requirements of DIN ISO 2768 m unless otherwise stated. For all ICK S types DIN ISO 2768c is valid.
- 6. The lengths of extruded profiles [|++|] and the pin layouts [] indicate only the standard range. We offer every profile cut to customer's exact length and machining requirement made to drawing or sample. We bore, countersink, mill, saw, grind and cut threads into your heat sink to meet your specific requirements. With our modern machine tools including CNC machining centres, multispindled drills (up to 26 drillings/threads at the same time) and digital milling and stamping tools plus our own "in house" tool room we are able to manufacture competetively priced prototypes as well as batch and mass produced parts with short lead times.
- 7. The standard material of our heatsinks is warm age-hardened aluminium alloy according to EN AW 6060 T66 (former AlMgSi05 – F22 acc. to DIN 1748). Our standard surface treatments are raw degreased aluminium (Al) and black anodised (SA). On request, we anodise clear natural (ME) or decorative in any colour that is technically possible.
- 8. If you cannot find a suitable profile within our range of approx. 400 profiles, 13 small heatsinks and 50 finger shaped heatsinks, we can design and produce to your requirements. Please contact us at the start of your next project so that we can work together, either directly or through our representatives. Remember that we have the ability to find the solution for "your" cooling problem.
- 9. Note on tolerances

All dimensions given in this cataloque for products, items and machined parts are acc. to DIN ISO 2768 m if not otherwise stated. Not included are items like extruded profiles, diecasts, handles, vibration dumpers etc. for which different standards apply.

Update - January 2013

The information given in this catalogue were established and examined carefully.

Nevertheless, mistakes or printing errors, and especially technical modifications and updating and improvement of our products, cannot be excluded.

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Heatsinks for SSR Die-cast heatsinks Assigment table Order example

Α4

fischer elektronik D **Technical introduction**

General information

Blind holes are produced after anodising. Through holes are produced before anodising. With completely visual parts, additional painting is recommended. The sections are extruded according to DIN EN 12020. For sections that exceed a circumscribed circle of 300 mm, DIN EN 755 apply. The machining tolerances are specified according to DIN ISO 2768 m.

Visual parts: Please indicate at which place clamp points are allowed! We recommend e.g. supplementary laquering.



9,6

8,4

A 5	Standard aluminium profiles Extruded heatsinks Lamella heatsinks		Thermal conductive material Hole pattern Drilling pattern for SSR	$\begin{array}{c} \rightarrow E \ 2 - 22 \\ \rightarrow A \ 21 \\ \rightarrow A \ 12 \end{array}$
	Fluid coolers	→ A 129 - 131	Technical introduction	\rightarrow A 2 - 7

С

R

Technical introduction

Information for dimensioning, shown on SK 47 general:

The deflection can be up to 0.8 mm concave, 0.2 mm convex. If a certain flatness of the bottom surface is required the bottom thickness can be decreased by a maximum of approx. 0.8 mm by means of face-milling. This situation must be taken into consideration with the bore hole depths for blind holes.

Counterbores and bore hole diameters are to be produced according to DIN 74, if not explicitly stated otherwise. The depth of thread should be calculated as follows.

Example M 5:

thread: $\langle M \rangle 5 \times 1.6 \text{ mm} = 8 \text{ mm}$

core bore: 8 mm + 2 mm = 10 mm

Examples:

cutout A: Through-hole according to DIN 74 A m 3, counterbore bottom side, undercut of the fins.

- cutout B: Through hole with break-through of the fins according to DIN 74 H m 4, counterbore on fin side.
- cutout C: Thread M 6. Depth of thread 1.6×6 mm = 9.6 mm, bore depth 9.6 mm + 2 mm = 11.6 mm.
- Bore hole on fin base is plunged through. Face counterbore dia. 12 x 0.5 on bottom side.
- cutout D: Blind thread M 4. Depth of thread 1.6 x 4 mm = 6.4 mm, bore depth 6.4 mm + 2 mm = 8.4 mm.

Extrusion tolerances – production tolerances

There is often the problem, that the production tolerances cannot be adhered to, due to the extrusion tolerances. The two examples show how the production tolerances can be cut in half by means of suitable dimensioning (here: extension of the zero point from the outer edge to the center of the section).

When taking unfavourable extrusion tolerances into consideration a difference of 1.1 mm arises between the two types of dimensioning with respect to the axis of symmetry.



fischer elektronik 2 **Technical introduction**

SK 34

G





extrusion tolerance \pm 0.8 mm

dimensioning set to the outer edges

dimensioning set to the center

When taking unfavourable extrusion tolerances into consideration, a difference of 0.4 mm arises between the two types of dimensioning with respect to the axis of symmetry.

Milling

If, when milling heatsinks, cooling aggregates, etc., the milling tool diameter is smaller than the area being milled for production reasons, so called "milling grooves" with steps or edges are produced (see sketch). Even if the roughness depth value for the surface is observed, it is a good idea to specify the area of the component in which no milling edges are allowed.



Heatsinks for solid state relays



- universal clip fastening, suitable for all 35 mm mounting rails
 according to DIN EN 50 022, rail thickness from 1 to 2.3 mm → E 23
- fast and simple asssembly of heatsinks by means of snapping them onto the mounting rail
- secure hold due to a stable extruded profile with integral stainless steel spring
- special lengths (≥ 40mm) and drillings on request





Examples of mounting rail versions suitable for KL 35

surface:

finish clear anodised

A11

Distance sleeves	→ E 30 - 37
Fastening for mounting rail	→ E 23
Guide rails for PCBs	→ E 24 - 28
Mounting material for semiconduct.	→ E 42 - 46

Spacers Mica wafers Aluminium oxide wafers Technical introduction $\begin{array}{r} \rightarrow E 38 \\ \rightarrow E 17 \\ \rightarrow E 15 - 16 \\ \rightarrow A 2 - 7 \end{array}$

C

D

C

H

Κ

Heatsinks for solid state relays

perforations	tions s KL 35 bez KL 35				
 drilling pattern rotated by 90° as well as further drilling patterns upon request 	 fixing of the SSR by means of screws with the help of insert nuts in the heatsink 	 fixing of the SSR by means of screws with the help of tapped holes in the heatsink 	 fixing of the SSR by means of screws with the help of tapped holes in the heatsink 		
	Art. Nr.	Art. Nr.	Art. Nr.		
SSR 1	SK 172 - 75 KL SSR 1	SK 89 - 75 KL SSR 1 SK 89 - 100 KL SSR 1 SK 111 - 75 KL SSR 1 SK 434 - 75 KL SRR 1 SK 453 - 75 KL SRR 1 SK 467 - 75 KL SRR 1 SK 507 - 75 KL SSR 1	SK 04 - 75 KL SSR 1 SK 33 - 75 KL SSR 1 SK 455 - 75 KL SSR 1 SK 467 - 75 KL SRR 1 SK 507 - 75 KL SRR 1		
SSR 2		SK 89 - 100 KL SSR 2 SK 89 - 150 KL SSR 2 SK 176 - 100 KL SSR 2	SK 04 - 150 KL SSR 2 SK 507 - 100 KL SSR 2 SK 507 - 150 KL SSR 2		
104.5 ₩ 92		SK 176 - 100 KL SSR 2 SK 176 - 150 KL SSR 2 SK 194 - 75 KL SSR 2 SK 507 - 100 KL SSR 2			
SSR 3	SK 187 - 75 KL SSR 3	SK 111 - 75 KL SSR 3	SK 48 - 50 KL SSR 3		
↓ ↓ + 17+ SSR 4	SK 172 - 150 KL SSR 4	SK 455 - 100 KL SSR 4	SK 455 - 100 KL SSR 4		
			SK 467 - 100 KL SSR 4		

Distance sleeves \rightarrow	E 30 - 37
Fastening for mounting rail \rightarrow	E 23
Guide rails for PCBs \rightarrow	E 24 - 28
Mounting material for semiconduct \rightarrow	E 42 - 46

Spacers Mica wafers Aluminium oxide wafers Mounting parts for heatsinks

 $\begin{array}{r} \rightarrow E 38 \\ \rightarrow E 17 \\ \rightarrow E 15 - 16 \\ \rightarrow A 2 - 7 \end{array}$

A 12

A

D

C

Ν

Fischer elektronik 23 Heatsinks

Hole pattern



CB = TO 3 + SOT 9 + TO 66 + SOT 32 at (↔) 37.5 mm oblique drilling



ø



TO 3 oblique drilling for 🖛 37.5 mm

SOT 32





TO 3 exceeding 🔶 50 mm





SOT 32 / TO 220 exceeding |+> 37.5 mm

Standard hole pattern are processed as complete pin layouts, centered on the length of the heatsink. Other positions of the pin layout on the heatsink, multiple drillings or changes of the drillings are processed according to customer's requirements.

For heatsinks exceeding 🖛 75 mm standard hole pattern can be supplied in multiple design.

Fixing slots



 ↔ [mm]	number of fixing slots
37,5	2
75	4

 ↔ [mm]	number of fixing slots
50	2
100	4

Heatsinks with the following shape _____ and a standard hole pattern have these fixing slots as part of the serial production

Order example

SK 01	50	SA	TO3	
profile	e length	surface	pin layout	

Surface treatment for heatsinks with standard drilling: black anodised (SA).

Raw degreased aluminium (AL) and clear natural anodise (ME) on request.

A 21	Extruded heatsinks Heatsinks for printed circuit boards Thermal conductive material Mount. material for semiconductors	→ E 2 - 22	Die-cast heatsinks Reating springs for transistors Lock-in transistor fixing spring Technical introduction	$ \begin{array}{r} \rightarrow A \ 123 - 126 \\ \rightarrow A \ 114 - 120 \\ \rightarrow A \ 84 - 88 \\ \rightarrow A \ 2 - 7 \end{array} $

D

M

N

Standard extruded heatsinks



A 35

Μ

Ν

High decorative surfaces	\rightarrow	A 9	Hee
Order example	\rightarrow	A 21	Hee
Heatsink as visual & decor-parts	\rightarrow	A 10	Spe
Drilling pattern for Solid State Rele	ais →	A 12	Tec

Heatsinks for Solid State Relay Heatsink special design Special profiles Technical introduction $\begin{array}{r} \rightarrow \quad A \ 11 - 12 \\ \rightarrow \quad A \ 135 - 136 \\ \rightarrow \quad A \ 138 \\ \rightarrow \quad A \ 2 - 7 \end{array}$

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C

D

C

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- 136

Standard extruded heatsinks



Ν

$\begin{array}{cccc} \hline & & & & & & & & & & & & & & & & & & $	A 77	High decorative surfaces Order example Heatsink as visual & decor-parts Drilling pattern for Solid State Rela	\rightarrow \rightarrow	A 9 A 21 A 10 A 12	Heatsinks for Solid State Relay Heatsink special design Special profiles Technical introduction	\rightarrow \rightarrow	A 11 – 12 A 135 – 136 A 138 A 2 – 7
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