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Small Size, Low-Power, Unidirectional, **CURRENT SHUNT MONITOR** Zerø-Drift Series

Check for Samples: INA216

FEATURES

- **CHIP-SCALE PACKAGE**
- COMMON-MODE RANGE: +1.8V to +5.5V
- OFFSET VOLTAGE: ±30µV
- GAIN ERROR: ±0.2% MAX
- CHOICE OF GAINS:
 - INA216A1: 25V/V
 - INA216A2: 50V/V
 - INA216A3: 100V/V
 - INA216A4: 200V/V
- QUIESCENT CURRENT: 13µA
- **BUFFERED VOLTAGE OUTPUT: No Additional Op Amp Needed**

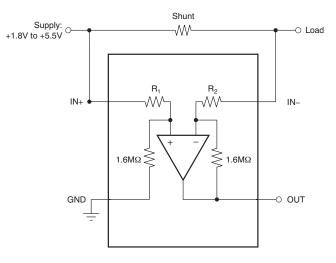
APPLICATIONS

- **NOTEBOOK COMPUTERS**
- **CELL PHONES**
- **TELECOM EQUIPMENT**
- POWER MANAGEMENT
- **BATTERY CHARGERS**

DESCRIPTION

The INA216 is a high-side voltage output current shunt monitor that can sense drops across shunts at common-mode voltages from +1.8V to +5.5V. Four fixed gains are available: 25V/V, 50V/V, 100V/V, and 200V/V. The low offset of the Zerø-Drift architecture enables current sensing with maximum drops across the shunt as low as 10mV full-scale, or with wide dynamic ranges of over 1000:1.

These devices operate from a single +1.8V to +5.5V power supply, drawing a maximum of 25µA of supply current. The INA216 series are specified over the temperature range of -40°C to +125°C, and offered in a chip-scale package.



PRODUCT	GAIN	R ₁ = R ₂
INA216A1	25	64kΩ
INA216A2	50	32kΩ
INA216A3	100	16kΩ
INA216A4	200	8kΩ

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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

FACKAGE INFORMATION ?							
PRODUCT	GAIN	PACKAGE-LEAD	PACKAGE DESIGNATOR	PACKAGE MARKING			
	25) (A)	WCSP-4	YFF	OW			
INA216A1	25V/V	ThinQFN-10	RSW	SNJ			
	50) (A (WCSP-4	YFF	OX			
INA216A2	50V/V	ThinQFN-10	RSW	SOJ			
	(00)////	WCSP-4	YFF	OY			
INA216A3	100V/V	ThinQFN-10	RSW	SPJ			
	000) (1) (WCSP-4	YFF	OZ			
INA216A4	200V/V	ThinQFN-10	RSW	SQJ			

PACKAGE INFORMATION⁽¹⁾

(1) For the most current package and ordering information see the Package Option Addendum at the end of this document, or visit the device product folder at www.ti.com.

ABSOLUTE MAXIMUM RATINGS⁽¹⁾

Over operating free-air temperature range, unless otherwise noted.

		INA216	UNIT
Supply Voltage		+7	V
Analog Inputs,	Differential (V _{IN+})–(V _{IN-})	-5.5 to +5.5	V
V _{IN+} , V _{IN-} ⁽²⁾	Common-Mode ⁽³⁾	GND-0.3V to +5.5	V
Output ⁽³⁾		GND-0.3V to (V+)+0.3	V
Input Current into Any Pin ⁽³⁾		5	mA
Operating Temperature		-55 to +150	°C
Storage Tempera	ature	-65 to +150	°C
Junction Temper	ature	+150	°C
	Human Body Model	2.5	kV
ESD Ratings:	Charged Device Model	1	kV
	Machine Model	200	V

(1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those specified is not implied.

(2) V_{IN+} and V_{IN-} are the voltages at the IN+ and IN- pins, respectively.

(3) Input voltage at any pin may exceed the voltage shown if the current at that pin is limited to 5mA.



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THERMAL INFORMATION

THERMAL METRIC ⁽¹⁾		INA216A1YFF, INA216A2YFF INA216A3YFF, INA216A3YFF, INA216A4YFF	UNITS
		4 PINS	
θ_{JA}	Junction-to-ambient thermal resistance	160	
$\theta_{JC(top)}$	Junction-to-case(top) thermal resistance	75	
θ_{JB}	Junction-to-board thermal resistance	76	°C/W
ΨJT	Junction-to-top characterization parameter	3	C/W
Ψ _{JB}	Junction-to-board characterization parameter	74	
$\theta_{JC(bottom)}$	Junction-to-case(bottom) thermal resistance	n/a	

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

THERMAL INFORMATION

	THERMAL METRIC ⁽¹⁾	INA216A1RSW, INA216A2RSW INA216A3RSW, INA216A4RSW	UNITS
		RSW	
		10 PINS	
θ_{JA}	Junction-to-ambient thermal resistance	114.9	
θ _{JC(top)}	Junction-to-case(top) thermal resistance	66.3	
θ_{JB}	Junction-to-board thermal resistance	21.4	°C/W
Ψ _{JT}	Junction-to-top characterization parameter	1.9	C/W
Ψ _{JB}	Junction-to-board characterization parameter	21.4	
θ _{JC(bottom)}	Junction-to-case(bottom) thermal resistance	N/A	

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

RSW PACKAGE ThinQFN-10 (TOP VIEW) $\mathrm{NC}^{(1)}$ $NC^{(1)}$ 6 NC⁽¹⁾ 8 5 IN-GND 4 9 IN-OUT 10 3 IN+ 2 NC⁽¹⁾ IN+

(1) No internal connection.

PIN CONFIGURATIONS

YFF PACKAGE WCSP-4 (TOP VIEW)						
IN-	A2 ()	B2 ()	OUT			
IN+	A1 ● ()	В1 ()	GND			

- (2) Bump side down. Drawing not to scale.
- (3) Power supply is derived from shunt (minimum common-mode range = 1.8V)

ELECTRICAL CHARACTERISTICS

Boldface limits apply over the specified temperature range, $T_A = -40^{\circ}C$ to $+125^{\circ}C$. At $T_A = +25^{\circ}C$ and $V_{CM} = V_{IN+} = 4.2V$, unless otherwise noted.

				INA216		
PARAMETER		CONDITIONS	NDITIONS MIN	ТҮР	MAX	UNIT
INPUT						
Offset Voltage, RTI ⁽¹⁾	V _{OS}					
INA216A1				±30	±100	μV
vs Temperature	dV _{os} /dT			0.06	0.2	μ ν/°C
INA216A2				±20	±75	μV
vs Temperature	dV _{os} /dT			0.05	0.25	μ ν/°C
INA216A3				±20	±75	μV
vs Temperature	dV _{os} /dT			0.03	0.25	μ ν/°C
INA216A4				±20	±75	μV
vs Temperature	dV _{os} /dT			0.1	0.3	μ ν/°C
Common-Mode Input Range	V _{CM}		1.8		5.5	V
Common-Mode Rejection ⁽²⁾	CMRR	V _{IN+} = +1.8V to +5.5V	90	108		dB
Power-Supply Rejection	PSRR		90	108		dB
Input Bias Current	I _{IN}			3		μA
OUTPUT	-1 - I		1		1 1	
Gain	G					
INA216A1				25		V/V
INA216A2				50		V/V
INA216A3				100		V/V
INA216A4				200		V/V
Gain Error						
INA216A1		$V_{OUT} = 0.2V$ to $V_{OUT} = 2.5V$		±0.01	±0.2	%
vs Temperature		V _{OUT} = 0.2V to V _{OUT} = 2.5V		0.01	0.025	m%/°C
INA216A2				0.05	±0.2	%
vs Temperature				0.017	0.1	m%/°C
INA216A3				0.06	±0.2	%
vs Temperature				0.023	0.1	m%/°C
INA216A4				0.03	±0.2	%
vs Temperature				0.076	0.3	m%/°C
Nonlinearity Error				±0.01		%
Maximum Capacitive Load		No sustained oscillation		750		pF
VOLTAGE OUTPUT ⁽³⁾		$R_L = 10k\Omega$ to GND				
Swing to V+ Power-Supply Ra	il			(V+) –0.1	(V+) –0.3	v
Swing to GND ⁽³⁾				(V _{GND}) +0.001	(V _{GND}) +0.002	v
Output Impedance				42		Ω
FREQUENCY RESPONSE						
Bandwidth	BW	$C_{LOAD} = 10 pF$				
INA216A1				20		kHz
INA216A2				10		kHz
INA216A3				5		kHz
INA216A4				2.5		kHz

RTI: Referred-to-input.
CMRR and PSRR are the same because V_{CM} is the supply voltage.
See Typical Characteristics graph, *Output Swing to Rail* (Figure 9).



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ELECTRICAL CHARACTERISTICS (continued)

Boldface limits apply over the specified temperature range, $T_A = -40^{\circ}C$ to $+125^{\circ}C$. At $T_A = +25^{\circ}C$ and $V_{CM} = V_{IN+} = 4.2V$, unless otherwise noted.

			INA216			
PARAMETER		CONDITIONS	MIN	MIN TYP		UNIT
FREQUENCY RESPONSE, con	tinued	•				
Slew Rate	SR			0.03		V/µs
NOISE, RTI ⁽⁴⁾						
Voltage Noise Density				60		nV/√Hz
POWER SUPPLY						
Specified Range	V _{IN+}		+1.8		+5.5	v
Quiescent Current	١ _Q			13	25	μA
Over Temperature					30	μΑ
TURN-ON TIME		$V_{IN+} = 0$ to +2.5V; $V_{SENSE} = 10mV$; $V_{OUT} \pm 0.5\%$		200		μs
TEMPERATURE RANGE						
Specified Temperature Range			-40		+125	°C

(4) RTI: Referred-to-input.

EXAS ISTRUMENTS

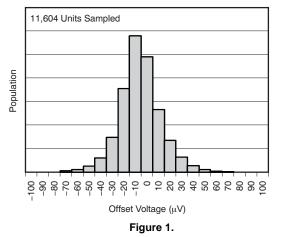
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TYPICAL CHARACTERISTICS

The INA216A1 is used for typical characteristic measurements at $T_A = +25^{\circ}C$, $V_S = +4.2V$, unless otherwise noted.

INPUT OFFSET VOLTAGE PRODUCTION DISTRIBUTION



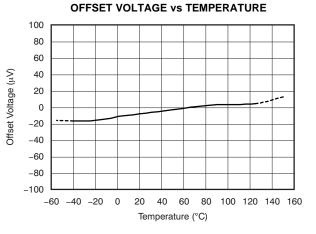


Figure 2.

GAIN ERROR vs TEMPERATURE

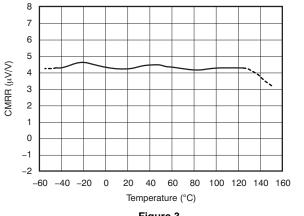
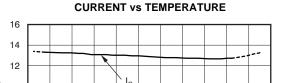
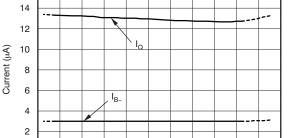


Figure 3.

QUIESCENT CURRENT AND NEGATIVE INPUT BIAS

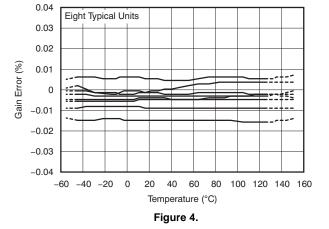




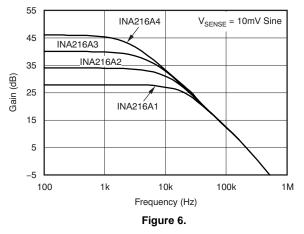


100 120 140 160

40 60 80



GAIN vs FREQUENCY



COMMON-MODE REJECTION RATIO vs TEMPERATURE

0

-60 -40 -20

0

20

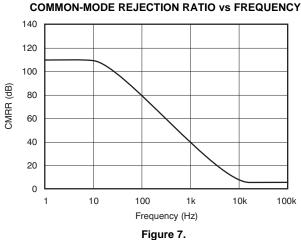


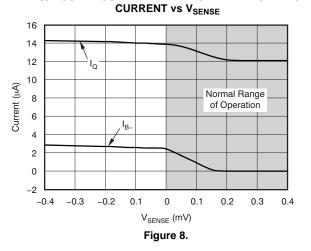
QUIESCENT CURRENT AND NEGATIVE INPUT BIAS

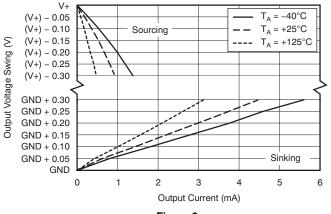
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TYPICAL CHARACTERISTICS (continued)

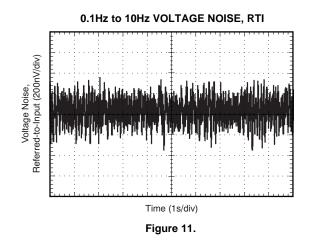
The INA216A1 is used for typical characteristic measurements at $T_A = +25^{\circ}C$, $V_S = +4.2V$, unless otherwise noted.



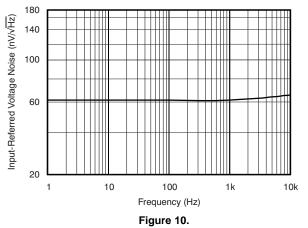








INPUT-REFERRED VOLTAGE NOISE vs FREQUENCY



STEP RESPONSE (80mV_{PP} Input Step)

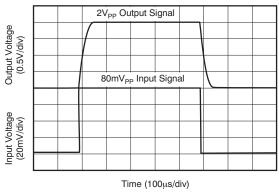
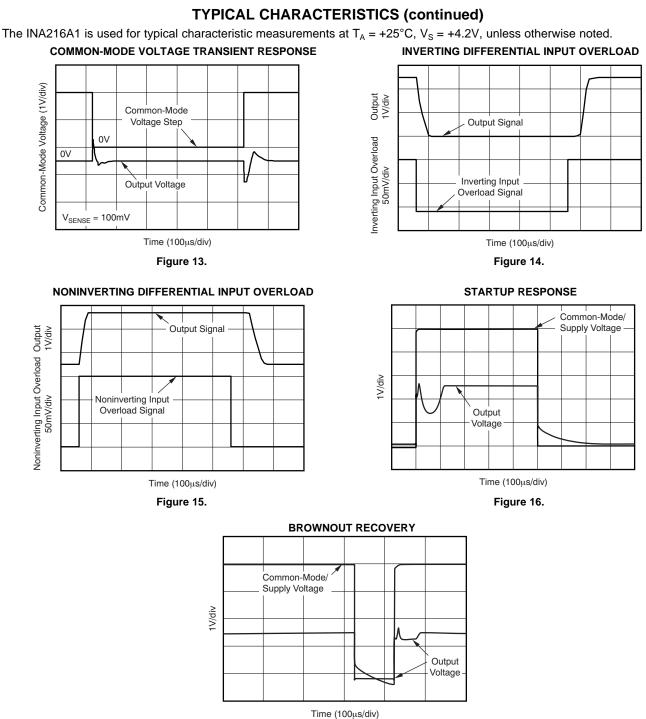


Figure 12.

OUTPUT VOLTAGE SWING vs OUTPUT CURRENT



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APPLICATION INFORMATION

Basic Connections

Figure 18 shows the basic connections of the INA216. The input pins, IN+ and IN–, should be connected as closely as possible to the shunt resistor to minimize any resistance in series with the shunt resistance.

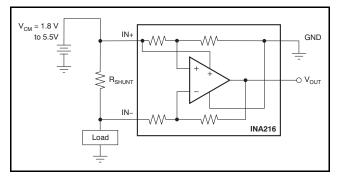


Figure 18. Typical Application

Figure 19 illustrates the INA216 connected to a shunt resistor with additional trace resistance in series with the shunt placed between where the current shunt monitors the input pins. With the typically low shunt resistor values commonly used in these applications, even small amounts of additional impedance in series with the shunt resistor can significantly affect the differential voltage present at the INA216 input pins.

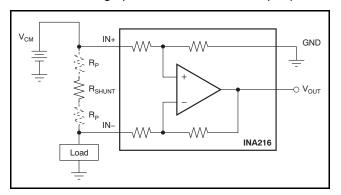


Figure 19. Shunt Resistance Measurement Including Trace Resistance, R_P

Figure 20 shows a proper Kelvin, or four-wire, connection of the shunt resistor to the INA216 input pins. This connection helps ensure that the only impedance between the current monitor input pins is the shunt resistor.

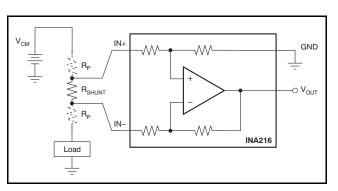


Figure 20. Shunt Resistance Measurement Using a Kelvin Connection

Power Supply

The INA216 does not have a dedicated power-supply pin. Instead, an internal connection to the IN+ pin serves as the power supply for this device. Because the INA216 is powered from the IN+ pin, the common-mode input range is limited on the low end to 1.8V. Therefore, the INA216 cannot be used as a low-side current shunt monitor.

Selecting R_s

The selection of the value of the shunt resistor (R_s) to use with the INA216 is based on the specific operating conditions and requirements of the application. The starting point for selecting the resistor is to first determine the desired full-scale output from the INA216. The INA216 is available in four gain options: 25, 50, 100, and 200. By dividing the desired full-scale output by each of the gain options, there are then four available differential input voltages that can achieve the desired full-scale output voltage, given that the appropriate gain device is used. With four values for the total voltage that is to be dropped across the shunt, the decision on how much of a drop is allowed in the application must be made. Most applications have a maximum drop allowed to ensure that the load receives the required voltage necessary to operate. Assuming that there are now multiple shunt voltages that are acceptable (based on the design criteria), the choice of what value shunt resistor to use can be made based on accuracy. As a result of the INA216 auto-zero architecture, the input offset voltage is extremely low. However, even the 100µV maximum input offset voltage specification plays a role in the decision of which shunt resistor value to choose. With a larger shunt voltage present at the current shunt monitor input, less error is introduced by the input offset voltage.

These comments have framed the decision on what the shunt resistor value should be, based on the full-scale value; but many applications require accurate measurements at levels as low as 10% of the full-scale value. At this level, the input offset voltage of the current shunt monitor becomes a larger percentage of the shunt voltage, and thus contributes a larger error to the output. The percentage of error created by the input offset voltage relative to the shunt voltage is shown in Equation 1.

$$Error_V_{OS} = \frac{V_{OS}}{V_{SENSE}} \bullet 100$$
(1)

Ideally, the differential input voltage at 10% would be increased to minimize the effects of the input offset voltage; however, we are bound by the full-scale value. The full-scale output voltage on the INA216 is limited to 200mV below the supply voltage (IN+). Selecting a shunt resistor to increase the shunt voltage at the low operating range of the load current could easily saturate the output of the current shunt monitor at the full-scale load current. For applications where accuracy over a larger range is needed, a lower gain option (and therefore, a larger differential input voltage) is selected. For applications where a minimal voltage drop on the line that powers the load is required, a higher gain option (and so, a smaller differential input voltage) is selected.

For example, consider a design that requires a full-scale output voltage of 4V, a maximum load current of 10A, and a maximum voltage drop on the common-mode line of 25mV. The 25mV maximum voltage drop requirement and a 4V full-scale output limits the gain option to the 200V/V device. A 100V/V setting would require a maximum voltage drop of 40mV with the other two lower gain versions creating larger voltage drops. Based on the gain of 200 on a 4V full-scale output, the maximum differential input voltage would be 20mV. The shunt resistor needed to create a 20mV drop with a 10A load current is $2m\Omega$.

When choosing the proper shunt resistor, it is also important to consider that at higher currents, the power dissipation in the shunt resistor becomes greater. Therefore, it is important to evaluate the drift of the sense resistor as a result of power dissipation, and choose an appropriate resistor based on its power wattage rating. www.ti.com

Calculating Total Error

The electrical specifications for the INA216 include the typical individual errors terms such as gain error, offset error, and nonlinearity error. Total error including all of these individual error components is not specified in the *Electrical Characteristics* table. To accurately calculate the error that can be expected from the device, we must first know the operating conditions to which the device is subjected. Some current shunt monitors specify a total error in the product data sheet. However, this total error term is accurate under only one particular set of operating conditions. Specifying the total error at this one point has little practical value, though, because any deviation from these specific operating conditions no longer yields the same total error value. This section discusses the individual error sources. with information on how to apply them in order to calculate the total error value for the device under normal operating conditions.

The typical error sources that have the largest impact on the total error of the device are input offset voltage, common-mode voltage rejection, gain error, and nonlinearity error.

The nonlinearity error of the INA216 is relatively low compared to the gain error specification, which results in a gain error that can be expected to be relatively constant throughout the linear input range of the device. While the gain error remains constant across the linear input range of the device, the error associated with the input offset voltage does not. As the differential input voltage developed across a shunt resistor at the input of the INA216 decreases, the inherent input offset voltage of the device becomes a larger percentage of the measured input signal, resulting in an increase in measurement error. This varying error is present among all current shunt monitors, given the input offset voltage ratio to the voltage being sensed by the device. The low input offset voltages present in the INA216 devices, however, limit the amount of contribution the offset voltage has on the total error term.

Two examples are provided that detail how different operating conditions can affect the total error calculations. Typical and maximum calculations are shown as well to provide the user more information on how much error variance could be present from device to device.



www.ti.com Example 1

Conditions: INA216A3; $V_{CM} = V_S = 3.3V$; $V_{SENSE} = 20mV$

TERM	LABEL	EQUATION	TYPICAL	MAXIMUM		
Maximum initial input offset voltage	VIO	—	20µV	75µV		
Added input offset voltage as result of common-mode voltage	VIO_CM	$\frac{1}{10^{\left(\frac{CMRR,dB}{20}\right)}} \bullet 4.2V - V_{CM} $	3.6µV	28µV		
Total input offset voltage	VIO_Total	$\sqrt{(VIO)^2 + (VIO_CM)^2}$	20µV	80µV		
Error because of input offset voltage	Error_VIO	VIO_Total V _{SENSE} • 100	0.1%	0.4%		
Gain error	Error_Gain	_	0.06%	0.2%		
Nonlinearity error	Error_Lin	—	0.01%	0.01%		
Total error		$\sqrt{(\text{Error_VIO})^2 + (\text{Error_Gain})^2 + (\text{Error_Lin})^2}$	0.12%	0.45%		

Table 1. Example 1

Example 2

Conditions: INA216A1; $V_{CM} = V_S = 5V$; $V_{SENSE} = 160mV$

Table 2. Example 2

TERM	LABEL	EQUATION	TYPICAL	MAXIMUM
Maximum initial input offset voltage	VIO	—	30µV	100µV
Added input offset voltage as result of common-mode voltage	VIO_CM	$\frac{1}{10^{\left(\frac{CMRR-dB}{20}\right)}} \bullet 4.2V - V_{CM} $	3.1µV	25.2µV
Total input offset voltage	VIO_Total	$\sqrt{(VIO)^2 + (VIO_CM)^2}$	30µV	100µV
Error because of input offset voltage	Error_VIO	VIO_Total V _{SENSE} • 100	0.02%	0.06%
Gain error	Error_Gain	_	0.01%	0.2%
Nonlinearity error	Error_Lin	_	0.01%	0.01%
Total error		$\sqrt{(\text{Error_VIO})^2 + (\text{Error_Gain})^2 + (\text{Error_Lin})^2}$	0.025%	0.21%

Input Filtering

An ideal location where filtering is implemented is at the inputs for a device. Placing an input filter in front of the INA216, though, is not recommended but can be implemented if it is determined to be necessary. This location is not recommended for filtering because adding input filters induces an additional gain error to the device that can easily exceed the device maximum gain error specification of 0.2%. In the INA216, the nominal current into the IN+ pin is in the range of 13µA while the bias current into the INpin is in the range of approximately 3µA. The current flowing into the IN+ pin includes both the input bias current as well as the quiescent current. Where the issue of input filtering begins to become more of an issue is that as the guiescent current of the INA216 also flows through the IN+ pin, when the output begins to drive current, this additional current also flows through the IN+ pin, creating an even larger error.

Placing a typical common-mode filter of 10Ω in series with each input and a 0.1μ F capacitor across the input pins, as shown in Figure 21, introduces an additional gain error into the system. For example, consider an application using the INA216A3 with a full-scale output of 4V, assuming that the device is not driving any output current. The shunt voltage needed to create the 4V output with a gain of 100 is 40mV. With 10Ω filter resistors on each input, there is a difference voltage created that subtracts from the 40mV full-scale differential current. The error can be calculated using Equation 2.

 $Error_R_{FILTER} = \frac{(I_{IN+} - I_{IN-}) \bullet R_{FILTER}}{V_{SHUNT}} \bullet 100$ (2)

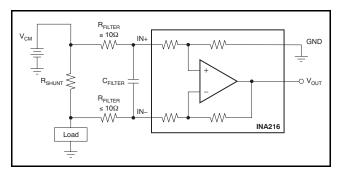


Figure 21. Input Filter

As mentioned previously, the current flowing into the IN+ pin increases once the output begins to drive current because of the quiescent current also flowing into the IN+ pin. The previous example resulted in an additional gain error of 0.3% as a result of the 10Ω filter resistors (assuming the output stage was not



driving any current). Connecting a $100k\Omega$ load to the 4V output now increases the current by an additional 40µA. This increase in current flowing through the IN+ pin would change the additional gain error from 0.3% to 1.3%.

If filtering is required for the application and the gain error introduced by the input filter resistors exceeds the available error budget for this circuit, a filter can be implemented following the INA216. Placing a filter at the output of the current shunt monitor is not typically the ideal location because the benefit of the low impedance output of the amplifier is lost. Applications that require the low impedance output require an additional buffer amplifier that follows the post current shunt monitor filter.

Using the INA216 With Transients Above 5.5V

With a small amount of additional circuitry, INA216 can be used in circuits subject to transients higher than 5.5V. Use only zener diode or zener-type transient absorbers, which are sometimes referred to as Transzorbs. Any other type of transient absorber has an unacceptable time delay. To use these protection devices, resistors are required in series with the INA216 inputs, as shown in Figure 22. These resistors serve as a working impedance for the zener. It is desirable to keep these resistors as small as possible because of the error described in the Input Filtering section. These protection resistors are most often around 10Ω . Larger values can be used with a greater impact to the total gain error. Because this circuit limits only short-term transients, many applications are satisfied with a 10^Ω resistor along with conventional zener diodes of the lowest power rating that can be found. This combination uses the least amount of board space. These diodes can be found in packages as small as SOT-523 or SOD-523. The use of these protection components may allow the INA216 to survive from being damaged in environments where large transients are common.

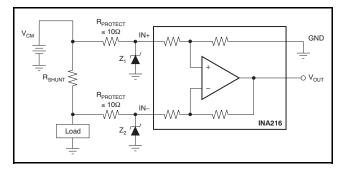
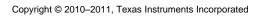


Figure 22. Transient Protection Using Dual Zener Diodes



REVISION HISTORY

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

С	Changes from Revision B (June 2010) to Revision C				
•	Changed product status from Mixed Status to Production Data	1			
•	Updated Package Information table to include RSW package information	2			
•	Added Thermal Information table for RSW package	3			
•	Added RSW package pinout drawing	3			

Changes from Revision A (June, 2010) to Revision B

•	Removed product preview status of INA216A2, INA216A3, and INA216A4 devices	2
•	Added offset voltage specifications for INA216A2, INA216A3, and INA216A4	4
•	Added gain and gain error specifications for INA216A2, INA216A3, and INA216A4	4
•	Added bandwidth specifications for INA216A2, INA216A3, and INA216A4	4
•	Updated graph grid for Figure 2 through Figure 5	6
•	Revised Table 1 and Table 2	11
•	Changed description of nominal current into IN+ pin to 13µA and bias current into IN– pin to 3µA	12



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PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package Drawing	Pins	-	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		-		Qty	(2)	(6)	(3)		(4/5)	
INA216A1RSWR	ACTIVE	UQFN	RSW	10	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	SNJ	Samples
INA216A1RSWT	ACTIVE	UQFN	RSW	10	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	SNJ	Samples
INA216A1YFFR	ACTIVE	DSBGA	YFF	4	3000	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OW	Samples
INA216A1YFFT	ACTIVE	DSBGA	YFF	4	250	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OW	Samples
INA216A2RSWR	ACTIVE	UQFN	RSW	10	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	SOJ	Samples
INA216A2RSWT	ACTIVE	UQFN	RSW	10	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	SOJ	Samples
INA216A2YFFR	ACTIVE	DSBGA	YFF	4	3000	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OX	Samples
INA216A2YFFT	ACTIVE	DSBGA	YFF	4	250	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OX	Samples
INA216A3RSWR	ACTIVE	UQFN	RSW	10	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	SPJ	Samples
INA216A3RSWT	ACTIVE	UQFN	RSW	10	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	SPJ	Samples
INA216A3YFFR	ACTIVE	DSBGA	YFF	4	3000	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OY	Samples
INA216A3YFFT	ACTIVE	DSBGA	YFF	4	250	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OY	Samples
INA216A4RSWR	ACTIVE	UQFN	RSW	10	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	SQJ	Samples
INA216A4RSWT	ACTIVE	UQFN	RSW	10	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	SQJ	Samples
INA216A4YFFR	ACTIVE	DSBGA	YFF	4	3000	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OZ	Samples
INA216A4YFFT	ACTIVE	DSBGA	YFF	4	250	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 125	OZ	Samples

⁽¹⁾ The marketing status values are defined as follows: **ACTIVE:** Product device recommended for new designs.





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LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect. NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design. PREVIEW: Device has been announced but is not in production. Samples may or may not be available. OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free** (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

⁽³⁾ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

⁽⁴⁾ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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TAPE AND REEL INFORMATION





QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



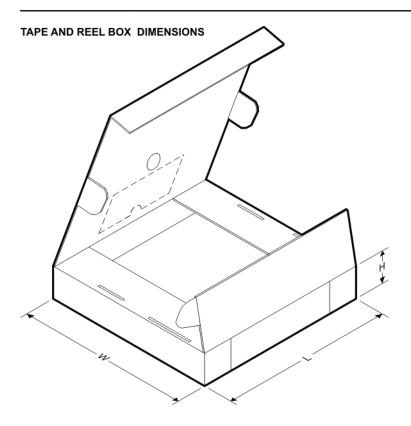
Device	Package		Pins	SPQ	Reel Diameter	Reel Width	A0 (mm)	B0 (mm)	K0	P1	W (mm)	Pin1 Quadrant
	Туре	Drawing			(mm)	W1 (mm)	(mm)	(mm)	(mm)	(mm)	(mm)	Quadrant
INA216A1RSWR	UQFN	RSW	10	3000	179.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A1RSWT	UQFN	RSW	10	250	179.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A1YFFR	DSBGA	YFF	4	3000	180.0	8.4	0.89	0.89	0.58	4.0	8.0	Q1
INA216A1YFFT	DSBGA	YFF	4	250	180.0	8.4	0.85	0.85	0.64	4.0	8.0	Q1
INA216A2RSWR	UQFN	RSW	10	3000	179.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A2RSWT	UQFN	RSW	10	250	179.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A2YFFR	DSBGA	YFF	4	3000	180.0	8.4	0.85	0.85	0.72	2.0	8.0	Q1
INA216A3RSWR	UQFN	RSW	10	3000	179.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A3RSWT	UQFN	RSW	10	250	179.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A3YFFR	DSBGA	YFF	4	3000	180.0	8.4	0.85	0.85	0.64	4.0	8.0	Q1
INA216A3YFFT	DSBGA	YFF	4	250	180.0	8.4	0.85	0.85	0.64	4.0	8.0	Q1
INA216A4RSWR	UQFN	RSW	10	3000	179.0	8.4	1.7	2.1	0.7	4.0	8.0	Q1
INA216A4YFFR	DSBGA	YFF	4	3000	180.0	8.4	0.85	0.85	0.72	2.0	8.0	Q1
INA216A4YFFT	DSBGA	YFF	4	250	180.0	8.4	0.85	0.85	0.72	2.0	8.0	Q1

TEXAS INSTRUMENTS

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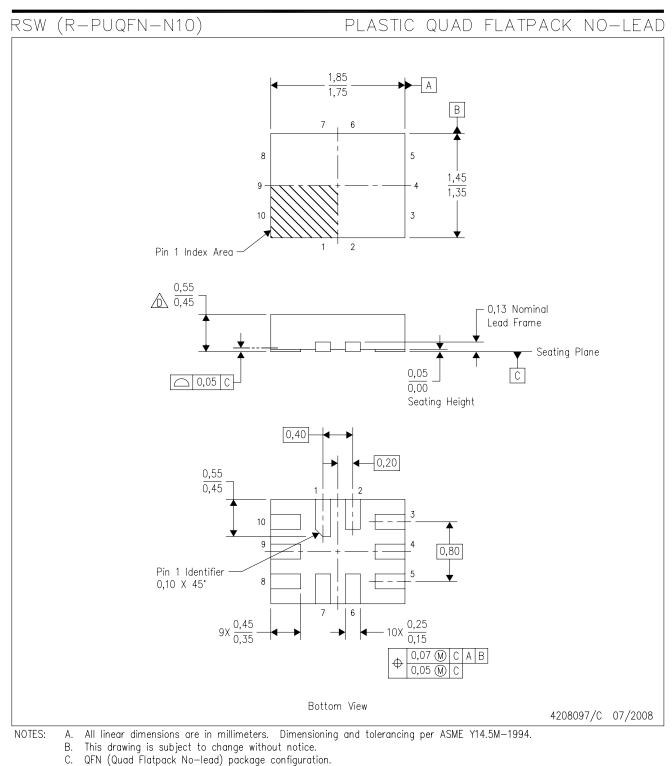
PACKAGE MATERIALS INFORMATION

4-Mar-2017



All dimensions are nominal							
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
INA216A1RSWR	UQFN	RSW	10	3000	203.0	203.0	35.0
INA216A1RSWT	UQFN	RSW	10	250	203.0	203.0	35.0
INA216A1YFFR	DSBGA	YFF	4	3000	210.0	185.0	35.0
INA216A1YFFT	DSBGA	YFF	4	250	210.0	185.0	35.0
INA216A2RSWR	UQFN	RSW	10	3000	203.0	203.0	35.0
INA216A2RSWT	UQFN	RSW	10	250	203.0	203.0	35.0
INA216A2YFFR	DSBGA	YFF	4	3000	182.0	182.0	20.0
INA216A3RSWR	UQFN	RSW	10	3000	203.0	203.0	35.0
INA216A3RSWT	UQFN	RSW	10	250	203.0	203.0	35.0
INA216A3YFFR	DSBGA	YFF	4	3000	182.0	182.0	20.0
INA216A3YFFT	DSBGA	YFF	4	250	182.0	182.0	20.0
INA216A4RSWR	UQFN	RSW	10	3000	203.0	203.0	35.0
INA216A4YFFR	DSBGA	YFF	4	3000	182.0	182.0	20.0
INA216A4YFFT	DSBGA	YFF	4	250	182.0	182.0	20.0

MECHANICAL DATA

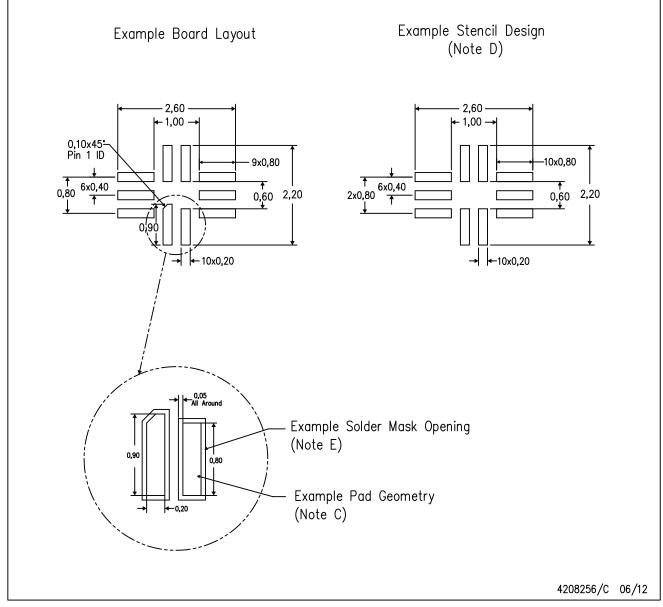


This package complies to JEDEC MO-288 variation UDEE, except minimum package height.



RSW (R-PUQFN-N10)

PLASTIC QUAD FLATPACK NO-LEAD



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
- E. Customers should contact their board fabrication site for minimum solder mask web tolerances between signal pads.



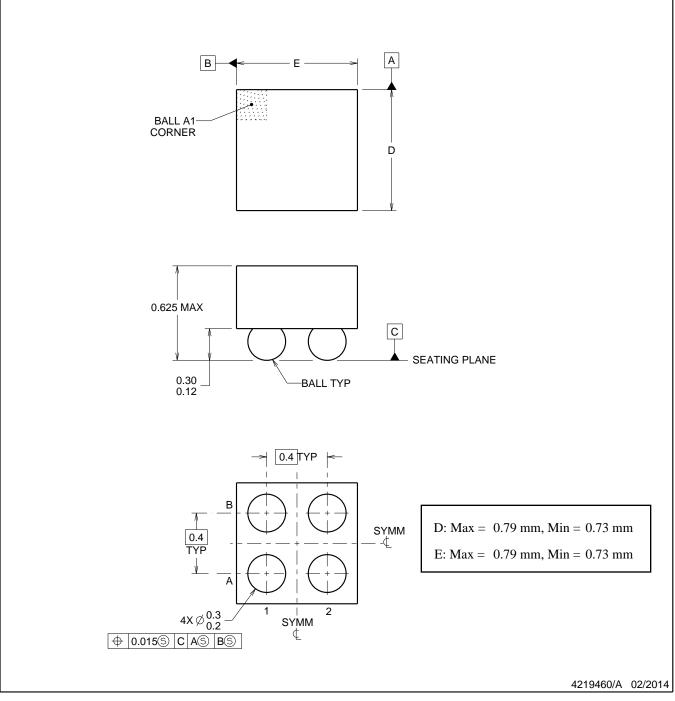
YFF0004



PACKAGE OUTLINE

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



NOTES:

NanoFree Is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.
- 3. NanoFree[™] package configuration.

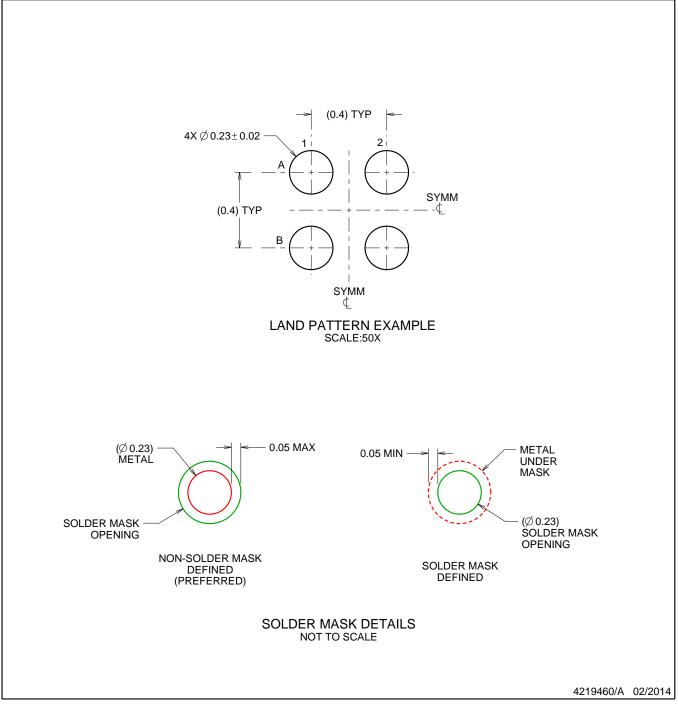


YFF0004

EXAMPLE BOARD LAYOUT

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



NOTES: (continued)

 Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. For more information, see Texas Instruments literature number SBVA017 (www.ti.com/lit/sbva017).

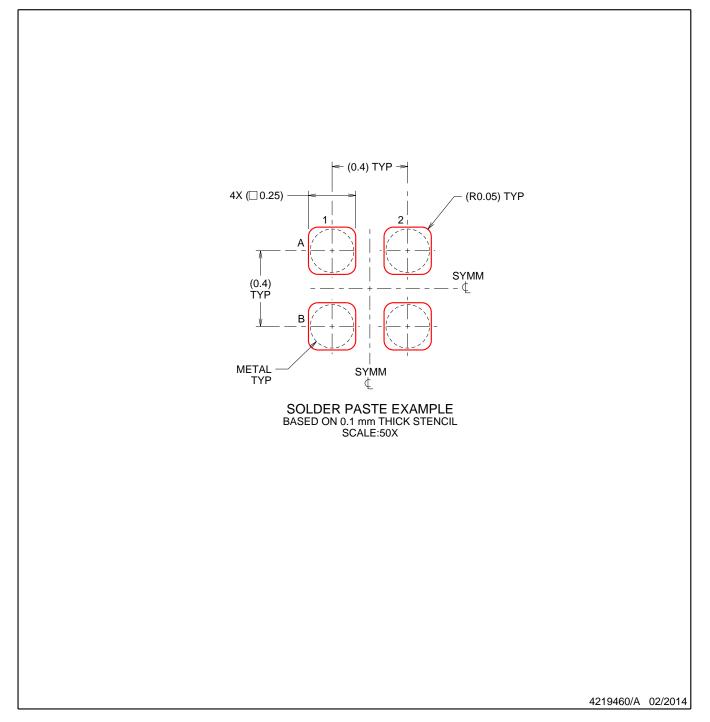


YFF0004

EXAMPLE STENCIL DESIGN

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.



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